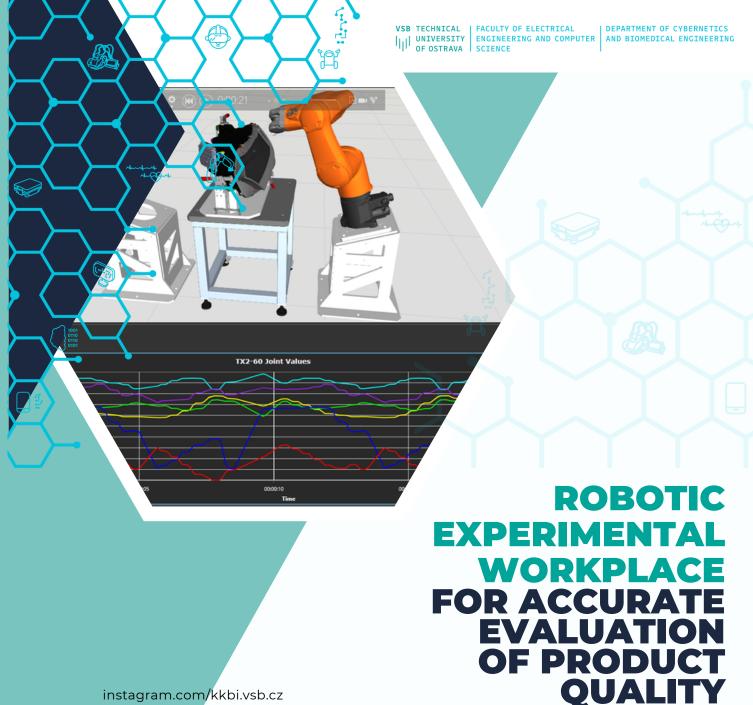
Contact

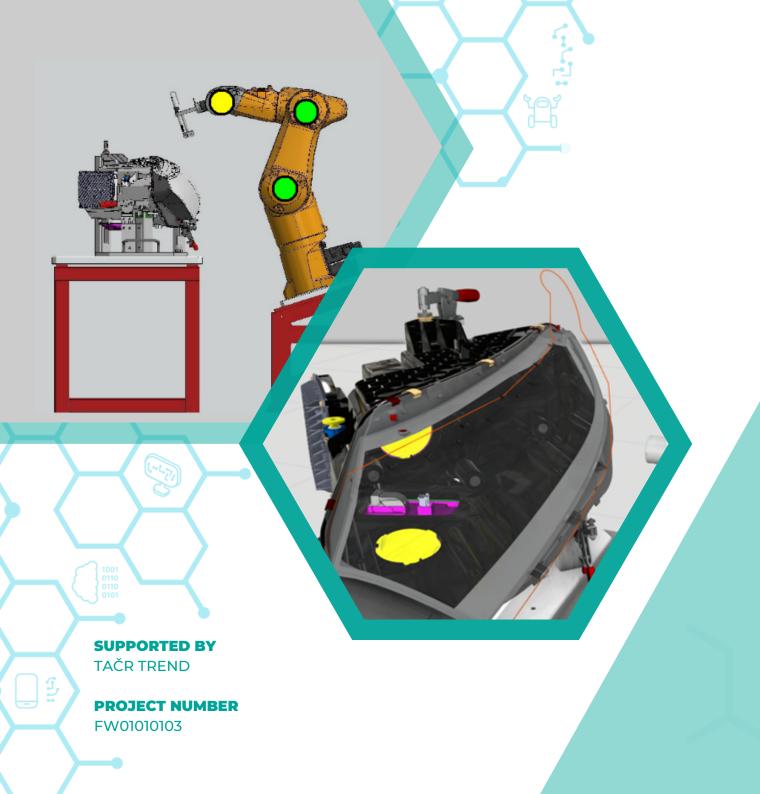
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Duration:

01/2020 06/2023

Research for production and testing functionality of an automated workplace prototype solution for evaluating the accuracy and quality of parts and components in serial production. The prototype solution consists of a six-axis robotic arm equipped with sensors.

The implementation of this project can gain knowledge for the development of unique automated production and testing equipment with a significant increase in the accuracy of autonomous navigation in the process of measurement and calibration.